RISK MEASURES IN FINITE STATE SPACES

CHRISTOS E. KOUNTZAKIS

1. FINANCIAL POSITIONS, ACCEPTANCE SETS AND COHERENT RISK MEASURES

Suppose that we live in an economic environment where there is a finite number of states $\Omega = \{1, 2, \ldots, S\}$ which may occur tomorrow (or after a certain period of time T). A financial position X is a random variable $X : \Omega \to \mathbb{R}$ which denotes either the terminal value of a portfolio or an investment at time-period T (if we put today to be the time-period 0) or the claim due to the occurence of one of the states in Ω . An acceptance set \mathcal{A} is a set of financial positions, claimed by the regulator as the 'safe' ones. However, financial risk according to the frame posed in [4] is the variability of the terminal value of some portfolio due to the presence of uncertainty. The essential properties that an acceptance set must satisfy, posed as axioms in [4] are the following:

(i)
$$\mathcal{A} + \mathcal{A} \subseteq \mathcal{A}$$

(ii) $\lambda \mathcal{A} \subseteq \mathcal{A}$ for any $\lambda \in \mathbb{R}_+$
(iii) $\mathbb{R}^{\mathcal{S}}_{\perp} \subset \mathcal{A}$

Note that by $(i), (ii) \mathcal{A}$ is a wedge. If \mathcal{A} is a cone, another property which concludes coherence of \mathcal{A} is

$$\mathcal{A} \cap (-\mathbb{R}^S_+) = \{0\}.$$

The three properties mentioned are directly related to the properties of Sub-additivity, Positive Homogeneity and Monotonicity of a coherent risk measure, as it is clear from the next definition of it. Also, a *numeraire asset* $e \in \mathbb{R}^{S}_{+}$ is used for *insuring* the financial positions with respect to some acceptance set \mathcal{A} . Insuring the financial position $x \in \mathbb{R}^{S}$ with respect to the pair (\mathcal{A}, e) is the determination of $\lambda \in \mathbb{R}$ shares of e such that

$$x + \lambda e \in \mathcal{A}$$

Here we suppose that the numeraire asset is the riskless investment $\mathbf{1} = (1, 1, ..., 1) \in \mathbb{R}^S$. A monetary (\mathcal{A}, e) -risk measure is a function $\rho : \mathbb{R}^S \to \mathbb{R}$ which indicates the minimum amount of shares $\rho(X)$ of e needed so that $X \in \mathbb{R}^S$ to become acceptable (insurable). The acceptance set of ρ is the set of positions

$$\mathcal{A}_{\rho} = \{ X \in \mathbb{R}^S | \rho(X) \le 0 \},\$$

being actually a *coherent acceptance set*, or else an acceptance set which satisfies the properties (i) - (iii) of the primary axioms in [4] whenever ρ is a coherent risk measure, according to the definition mentioned below. The *risk measure measure associated with the pair* (\mathcal{A}, e) is defined as follows:

$$\rho_{\mathcal{A},e}(x) = \inf\{m \in \mathbb{R} | x + m \cdot e \in \mathcal{A}\},\$$

for any $x \in \mathbb{R}^S$. As it is well known (see [4]), a risk measure $\rho : \mathbb{R}^S \to \mathbb{R}$ which satisfies the properties $(X, Y \in \mathbb{R}^S)$

- (i) $\rho(X + a\mathbf{1}) = \rho(X) a$ (Translation Invariance) (ii) $\rho(X + Y) \leq \rho(X) + \rho(Y)$ (Sub additivity)
- (*ii*) $\rho(X+Y) \le \rho(X) + \rho(Y)$ (Sub-additivity)

- (*iii*) $\rho(\lambda X) = \lambda \rho(X), \lambda \in \mathbb{R}_+$ (Positive Homogeneity) and
- (iv) $X \leq Y$ in terms of the usual partial ordering of \mathbb{R}^S , implies $\rho(Y) \leq \rho(X)$ (Monotonicity)

is called *coherent*.

In order to conclude on the relation between acceptance sets and risk measures we may prove a first proposition

Proposition 1.1. If \mathcal{A} is a closed cone of \mathbb{R}^S containing \mathbb{R}^S_+ , then the risk measure $\rho_{\mathcal{A},1}$ is a coherent risk measure which doesn't take infinite values.

Proof We have to verify that the properties of a coherent risk measure hold for $\rho_{\mathcal{A},\mathbf{1}}$. Note that according to the [9, Pr. 3.1.3], **1** is an order-unit of \mathbb{R}^S . Also, for any $X \in \mathbb{R}^S$ there is some $m \in \mathbb{R}$ such that $X + m\mathbf{1} \in \mathcal{A}$. That is because

$$\mathbb{R}^S = \bigcup_{n=1}^{\infty} [-n\mathbf{1}, \ n\mathbf{1}]_{\mathcal{A}},$$

where $[.,.]_{\mathcal{A}}$ denotes the corresponding order-interval with respect to the partial ordering induced on \mathbb{R}^S by \mathcal{A} . Hence for some $n(X) \in \mathbb{N}$,

$$X \in [-n(X)\mathbf{1}, \ n(X)\mathbf{1}]_{\mathcal{A}},$$

which implies $X + n(X)\mathbf{1} \in \mathcal{A}$ and the set $\{m \in \mathbb{R} \mid X + m\mathbf{1} \in \mathcal{A}\}$ is non-empty for any $X \in \mathbb{R}^S$. This also indicates that $\rho_{\mathcal{A},\mathbf{1}}(X) \neq \infty$ for any $X \in \mathbb{R}^S$.

In order to show that $\rho_{\mathcal{A},\mathbf{1}}(X) \neq -\infty$ for every $X \in \mathbb{R}^S$, we have to show that for any $X \in \mathbb{R}^S$, the set of real numbers $\{m \in \mathbb{R} \mid m\mathbf{1} + X \in \mathcal{A}\}$ is lower bounded. Since $\mathbf{1} \in int\mathbb{R}^S_+$, $\mathbf{1} \in int\mathcal{A}$, which implies that $\mathbf{1}$ is an order-unit of \mathbb{R}^S being partially ordered by the wedge \mathcal{A} . As we mentioned before, this implies that for any $X \in \mathbb{R}^S$ there is some $n(X) \in \mathbb{N}$ such that

$$X \in \left[-n(X)\mathbf{1}, \ n(X)\mathbf{1}\right],$$

where [.,.] denotes an order-interval with respect to the partial ordering induced by \mathcal{A} on \mathbb{R}^S . But on the other hand for any $X \in \mathbb{R}^S$ there is some nonzero $m_0(X) \in \mathbb{R}_+$ such that

$$X - m_0(X) \mathbf{1} \notin \mathcal{A}$$
.

If X = 0 this m_0 is any $\varepsilon > 0$. If $X \neq 0$ we suppose that such a positive real number does not exist, so we would have for any $\lambda > 0$, that

$$X - \lambda \mathbf{1} \in \mathcal{A}$$
.

Since $\mathbf{1} \in int\mathcal{A}$ we get the equality $\mathbb{R}^S = \bigcup_{n=1}^{\infty} [-n\mathbf{1}, n\mathbf{1}]_{\mathcal{A}}$. Suppose that $n(X) \in \mathbb{N}$ is some natural number such that

$$X \in \left[-n(X)\mathbf{1}, \ n(X)\mathbf{1}\right].$$

Since $X \ge n(X)e$ by assumption, we get that $n(X)\mathbf{1} \le X \le n(X)\mathbf{1}$ in terms of the partial ordering induced by \mathcal{A} on \mathbb{R}^S and because \mathcal{A} is a cone, it implies

$$X = n(X)\mathbf{1}.$$

But $X \in [-(n(X)+1)\mathbf{1}, (n(X)+1)\mathbf{1}]$ and by the same assumption $X \ge (n(X)+1)\mathbf{1}$ which implies by the same way that

$$X = (n(X) + 1)\mathbf{1},$$

which is a contradiction because if this is the case, we find X = 0. Hence, for any $X \neq 0$ there exists some nonzero $m_0(X) \in \mathbb{R}_+$ such that

$$X - m_0(X) \mathbf{1} \notin \mathcal{A}$$
.

After all, we remark that $-m_0(X)$ is a lower bound for the set $\{m \in \mathbb{R} \mid m\mathbf{1} + X \in \mathcal{A}\}$. If we suppose that there is some $k < -m_0(X)$ such that

$$k\mathbf{1} + X \in \mathcal{A}$$

then we come to a contradiction since then we would have

$$X - m_0(X)\mathbf{1} = X + k\mathbf{1} + (-m_0(X) - k)\mathbf{1} \in \mathcal{A}$$

from the well-known properties of a wedge, since $X + k\mathbf{1} \in \mathcal{A}$ by assumption and $(-m_0(X) - k)\mathbf{1} \in \mathcal{A}$ since $\mathbf{1} \in \mathcal{A}$ and $(-m_0(X) - k) > 0$. Finally, we found that $\rho_{\mathcal{A},\mathbf{1}}$ cannot take the value $-\infty$ if \mathcal{A} is a cone.

About the properties of a coherent risk measure, we have the following:

(*i*) (Translation Invariance):

$$\rho_{\mathcal{A},\mathbf{1}}(X+ae) = \inf\{m \in \mathbb{R} \mid (X+a\mathbf{1})+m\mathbf{1} \in \mathcal{A}\}$$
$$= \inf\{(m+a)-a \mid X+(m+a)\mathbf{1} \in \mathcal{A}\}$$
$$= \inf\{k \in \mathbb{R} \mid X+k\mathbf{1} \in \mathcal{A}\}-a=\rho_{\mathcal{A},\mathbf{1}}(X)-a,$$

for any $X \in \mathbb{R}^S$ and any $a \in \mathbb{R}$.

(*ii*) (Sub-additivity):

If $m_1 \in \{m \in \mathbb{R} \mid X + m\mathbf{1} \in \mathcal{A}\}$ and $m_2 \in \{m \in \mathbb{R} \mid Y + m\mathbf{1} \in \mathcal{A}\}$ then $m_1 + m_2 \in \{k \in \mathbb{R} \mid (X + Y) + k\mathbf{1} \in \mathcal{A}\}.$

It means

$$\rho_{\mathcal{A},\mathbf{1}}(X+Y) \le m_1 + m_2 \,.$$

Hence $\rho_{\mathcal{A},\mathbf{1}}(X+Y) - m_1 \leq m_2$ which implies

$$\rho_{\mathcal{A},\mathbf{1}}(X+Y) - m_1 \le \rho_{\mathcal{A},\mathbf{1}}(Y)$$

for any such m_1 . In the same way, by $\rho_{\mathcal{A},1}(X+Y) - \rho_{\mathcal{A},1}(Y) \leq m_1$ we obtain

$$\rho_{\mathcal{A},\mathbf{1}}(X+Y) - \rho_{\mathcal{A},\mathbf{1}}(Y) \le \rho_{\mathcal{A},\mathbf{1}}(X)$$

and the required property holds for any $X, Y \in \mathbb{R}^S$.

The above proof of sub-additivity holds in case where $X, Y \in \mathbb{R}^S$ are such that $\rho_{\mathcal{A},\mathbf{1}}(X+Y)$, $\rho_{\mathcal{A},\mathbf{1}}(X)$, $\rho_{\mathcal{A},\mathbf{1}}(Y) \in \mathbb{R}$. If $\rho_{\mathcal{A},\mathbf{1}}(X+Y) = -\infty$ and at least one of $\rho_{\mathcal{A},\mathbf{1}}(X)$, $\rho_{\mathcal{A},\mathbf{1}}(Y)$ is equal to $-\infty$ the sub-additivity holds. Note that if $\rho_{\mathcal{A},\mathbf{1}}(X+Y) = -\infty$ and $\rho_{\mathcal{A},\mathbf{1}}(X)$, $\rho_{\mathcal{A},\mathbf{1}}(Y) \in \mathbb{R}$ the sub-additivity property is also true. Finally we note that if for example $\rho_{\mathcal{A},\mathbf{1}}(X) = -\infty$ and $\rho_{\mathcal{A},\mathbf{1}}(Y) \in \mathbb{R}$, then $\rho_{\mathcal{A},\mathbf{1}}(X+Y) = -\infty$. This is true because since $\rho_{\mathcal{A},\mathbf{1}}(X) = -\infty$ there is a sequence $(a_n)_{n\in\mathbb{N}}$ of real numbers, such that $a_n \to -\infty$ and $X + a_n \mathbf{1} \in \mathcal{A}$. Also, since $\rho_{\mathcal{A},\mathbf{1}}(Y) \in \mathbb{R}$ consider some $a \in \mathbb{R}$ with $Y + a\mathbf{1} \in \mathcal{A}$. Then since for the sequence $(d_n)_{n\in\mathbb{N}}$ with $d_n = a_n + a$ for any $n \in \mathbb{N}$ $(X+Y)+(a_n+a)\mathbf{1} \in \mathcal{A}$ from the property $\mathcal{A}+\mathcal{A} \subseteq \mathcal{A}$ of \mathcal{A} , while $lim_n(a_n+a) = -\infty$, we get $\rho_{\mathcal{A},\mathbf{1}}(X+Y) = -\infty$. In case where \mathcal{A} is a cone, this point may be omitted since $\rho_{\mathcal{A},\mathbf{1}}$ takes only finite values.

(*iii*) (Positive Homogeneity):

For $\lambda = 0$ we have that $\rho_{\mathcal{A},\mathbf{1}}(0) \leq 0$, since $0 \in \{m \in \mathbb{R} \mid 0 + m\mathbf{1} \in \mathcal{A}\}$. If we suppose that $\rho_{\mathcal{A},\mathbf{1}}(0) < 0$, then for $\delta = -\rho_{\mathcal{A},\mathbf{1}}(0)$ and by the definition of $\rho_{\mathcal{A},\mathbf{1}}(0)$ as the infimum of a subset of the real numbers, there is some $m_{\delta} \in \{m \in \mathbb{R} \mid 0 + m\mathbf{1} \in \mathcal{A}\}$ such that

$$m_{\delta} < \rho_{\mathcal{A},\mathbf{1}}(0) + \delta = 0$$

Hence $m_{\delta} \mathbf{1} \in \mathcal{A}$ with $m_{\delta} < 0$. But from the properties of a wedge, we also have that $m_{\delta} \mathbf{1} \in -\mathcal{A}$. Then,

$$\mathbf{1}\in\mathcal{A}\cap(-\mathcal{A})$$

because \mathcal{A} is a wedge, a contradiction since **1** is an interior point of \mathcal{A} . The contradiction is implied by the assumption that $\rho_{\mathcal{A},\mathbf{1}}(0) < 0$. This implies

$$\rho_{\mathcal{A},\mathbf{1}}(0) = 0\,,$$

and the positive homogeneity if $\lambda = 0$ holds.

If $\lambda > 0$ we remark that

 $\{\lambda m \in \mathbb{R} \mid m \in \mathbb{R} \text{ is such that } X + m\mathbf{1} \in \mathcal{A}\} \subseteq \{k \in \mathbb{R} \mid \lambda X + k\mathbf{1} \in \mathcal{A}\},\$

which implies the inequality

$$\rho_{\mathcal{A},\mathbf{1}}(\lambda X) \le \lambda \rho_{\mathcal{A},\mathbf{1}}(X)$$

We can also see that

$$\left\{\frac{k}{\lambda} \in \mathbb{R} \mid k \in \mathbb{R} \text{ is such that } \lambda X + k\mathbf{1} \in \mathcal{A}\right\} \subseteq \left\{m \in \mathbb{R} \mid X + m\mathbf{1} \in \mathcal{A}\right\}.$$

This last remark implies

$$\rho_{\mathcal{A},\mathbf{1}}(X) \leq \frac{\rho_{\mathcal{A},\mathbf{1}}(\lambda X)}{\lambda},$$

and from the above inequality, together with the relation (1.1), the required property is established for any $X \in \mathbb{R}^S$ and any $\lambda \in \mathbb{R}_+$.

(iv) (Monotonicity):

(1.2) If $Y \ge X$ with respect to the partial ordering induced on \mathbb{R}^S by \mathcal{A} we notice that $\{m \in \mathbb{R} \mid X + m\mathbf{1} \in \mathcal{A}\} \subseteq \{m \in \mathbb{R} \mid Y + m\mathbf{1} \in \mathcal{A}\}.$

Indeed, if $m_1 \in \{m \in \mathbb{R} \mid X + m\mathbf{1} \in \mathcal{A}\}$, then

(1.3)
$$X + m_1 \mathbf{1} \in \mathcal{A},$$

and since $Y \ge X$,

(1.1)

$$Y - X \in \mathcal{A}.$$

By the relations (1.3) and (1.4) we find that

$$Y + m_1 e \mathbf{1} = (Y - X) + (X + m_1 \mathbf{1}) \in \mathcal{A}$$

taking in account the properties of a cone. Hence $m_1 \in \{m \in \mathbb{R} \mid Y + m\mathbf{1} \in \mathcal{A}\}$ and the (1.2) is true. Therefore

$$\rho_{\mathcal{A},\mathbf{1}}(Y) \le \rho_{\mathcal{A},\mathbf{1}}(X) \,,$$

and the required property holds for any $X, Y \in \mathbb{R}^S$.

For the completeness of the above proof, the following lemma is needed

Lemma 1.2. If A is a wedge of the normed linear space L which is not a subspace of it, then if $X \in intA$ (where intA denotes the norm-interior of A), then $X \notin A \cap (-A)$.

Proof of Lemma 1.2 Let us suppose that there is a $X \in intA$ with $X \in A \cap (-A)$. Then there exists some $\delta > 0$ such that $X + B(0, \delta) \subseteq A$, where $B(0, \delta)$ denotes the open ball centered at 0 with radius equal to δ . Since A is not a subspace, then there exists some $X_0 \in (-A) \setminus A = (-A) \cap A^c$ where A^c is the set-theoretic complement of A. (If $(-A) \cap A^c = \oslash$ then A = (-A) which means that A is a subspace of L, a contradiction). Since $B(0, \delta)$ is an absorbing set, there is some $\lambda_{\delta} > 0$ such that $\lambda_{\delta}X_0 \in B(0, \delta)$. Then $X + \lambda_{\delta}X_0 \in (-A) \setminus A$. This is true, because (-A) is a wedge of L and since $X_0 \in -A$ then $\lambda_{\delta}X_0 \in -A$, while $X \in -A$, too. This implies $X + \lambda_{\delta}X_0 \in -A$. On the other hand, since we supposed that $X \in A \cap (-A)$, we have that $-X \in A$. If $X + \lambda_{\delta}X_0 \in A$, then we would have that $\lambda_{\delta}X_0 \in A + (-X) \subseteq A + A \subseteq A$. By the properties of a wedge we would also have that $X_0 = \frac{1}{\lambda_{\delta}}\lambda_{\delta}X_0 \in \frac{1}{\lambda_{\delta}}A \subseteq A$. But $X + \lambda_{\delta}X_0 \in X + B(0, \delta) \subseteq A$ from the fact that $X \in intA$, which implies a contradiction. The contradiction came as a consequence of the assumption that such a point X exists.

Hence $\rho_{\mathcal{A},\mathbf{1}}(X)$ for any $X \in \mathbb{R}^S$ is actually the minimum amount of money which makes X acceptable.

The second important proposition is the following.

Proposition 1.3. If ρ is coherent, then $\rho = \rho_{\mathcal{A}_{\rho}}$.

Proof. For any $X \in \mathbb{R}^S$,

$$\rho_{\mathcal{A}_{\rho}}(X) = \inf \{ \alpha \in \mathbb{R} | X + \alpha \mathbf{1} \in \mathcal{A}_{\rho} \}$$
$$= \inf \{ \alpha \in \mathbb{R} | \rho(X + \alpha \mathbf{1}) \leq 0 \} =$$
$$= \inf \{ \alpha \in \mathbb{R} | \rho(X) - \alpha \leq 0 \} = \rho(X).$$

Hence the interpretation of $\rho(X)$ as the minimum amount of money needed so that X is acceptable, holds for every coherent risk measure and for its own acceptance set \mathcal{A}_{ρ} . Namely, the meaning of the properties of a coherent risk measure from the aspect of insurance is the following:

- (i) Translation Invariance: If we incorporate an amount of money α in a financial position X, then the reduction to the amount of money needed so that the investment consisted by the position X and the amount α to be acceptable with respect to ρ is equal to α .
- (*ii*) Sub-additivity: Diversification of the investments reduces the risk (the total premium).
- (*iii*) Positive Homogeneity : The risk premium with respect to ρ for a position consisted by a long position on some shares $\lambda \geq 0$ on this position X is the premium of X with respect to ρ multiplied by λ .
- (iv) Monotonicity: Greater payoff means less need for insurance premium.

2. Properties of the coherent risk measures

For a coherent risk measure ρ , we name E_{ρ}^{*} the functional defined on \mathbb{R}^{S} such that

$$(2.1) E_{\rho}^*(X) = \rho(-X)$$

for every $X \in \mathbb{R}^S$ (we use the notation met in the proof of [4, Th. 4.1]). This functional enjoys the following properties $(X, Y \in \mathbb{R}^S)$

- (i) $E^*_{\rho}(aX + b\mathbf{1}) = aE^*_{\rho}(X) + b, \ a \in \mathbb{R}_+, b \in \mathbb{R}$ (Positive Affine Homogeneity) (ii) $E^*_{\rho}(X + Y) \le E^*_{\rho}(X) + E^*_{\rho}(Y)$ (Sub-additivity)
- (*iii*) $X \leq Y$ in terms of the usual partial ordering of \mathbb{R}^S implies $E^*_{\rho}(X) \leq E^*_{\rho}(Y)$ (Monotonicity)

The list of these properties may be found in [7], where such functionals are characterized as upper expectations (see [7, Pr. 2.1]), which are also used in the proof of [4, Pr. 4.1] for the characterization of a coherent risk measure as the 'worst expectation' on some non-empty set of probability vectors on the state space $\{1, 2, \ldots, S\}$. In [4, Pr. 2.2] is indicated that every coherent risk measure ρ is a continuous function, hence the acceptance set

(2.2)
$$\mathcal{A}_{\rho} = \left\{ X \in \mathbb{R}^{S} \, | \, \rho(X) \le 0 \right\},$$

associated with the risk measure ρ , is closed. In [4, Pr. 2.2] there is an assertion that this is a consequence of the convexity of ρ .

2.1. The continuity of coherent risk measures in Euclidean spaces. In the following Proposition we present a proof for the continuity of ρ deduced from its properties as coherent measure. For this purpose we are going to use the properties of the associated functional E_{ρ}^* .

Proposition 2.1. If ρ is a coherent risk measure, then the function $\rho : \mathbb{R}^S \to \mathbb{R}$ is Lipschitz.

Proof. We are going to prove that E_{ρ}^* , defined by (2.1), is a Lipschitz function. First, note that

$$E_{\rho}^{*}(X) \leq E_{\rho}^{*}(Y) + E_{\rho}^{*}(X - Y)$$

for any $X, Y \in \mathbb{R}^S$, from the sub-additivity of E_{ρ}^* . We can write

$$E_{\rho}^{*}(Y) \leq E_{\rho}^{*}(X) + E_{\rho}^{*}(Y - X)$$

for the same reason. We are going to show that

$$E_{\rho}^{*}(X - Y) \le A \|X - Y\|_{1}$$

and

$$E_{\rho}^{*}(Y - X) \le A \|Y - X\|_{1}$$

for some real number A > 0, where $\|.\|_1$ denotes the usual ℓ_1 norm for the vectors of \mathbb{R}^S . It suffices to show that for any $X \in \mathbb{R}^S$,

$$E^*_{\rho}(X) \le A \|X\|_1$$

holds for some A > 0. Consider the usual basis $\{e_1, e_2, \ldots, e_S\}$ of \mathbb{R}^S which corresponds to the so-called set of Arrow securities.

Let us suppose that $E_{\rho}^{*}(e_{s}) = 0$ for any state $s \in \{1, 2, \ldots, S\}$, then

(2.3)
$$E_{\rho}^{*}(\mathbf{1}) = E_{\rho}^{*}(\sum_{s=1}^{S} e_{s}) \le \sum_{s=1}^{S} E_{\rho}^{*}(e_{s}) = 0$$

by sub-additivity of E_{ρ}^* . But $1 \ge 0$ and from the monotonicity of E_{ρ}^* we get

(2.4)
$$E_{\rho}^{*}(\mathbf{1}) \ge 0$$
.

Hence by (2.3) and (2.4) we obtain $E^*_{\rho}(\mathbf{1}) = 0$. But from positive affine homogeneity of E^*_{ρ} we get

$$E_{\rho}^{*}(\mathbf{1}) = E_{\rho}^{*}(0+1\cdot\mathbf{1}) = 0E_{\rho}^{*}(0) + 1 = 1$$

thus we arrive at a contradiction. Therefore, a state s_0 such that $E^*_{\rho}(e_{s_0}) > 0$ exists. Note that from monotonicity we get $E^*_{\rho}(e_s) \ge 0$ for every state $s = 1, 2, \ldots, S$. We put

(2.5)
$$A := \max\{E_{\rho}^{*}(e_{s}) \mid s = 1, 2, \dots, S\} > 0$$

Then

$$E_{\rho}^{*}(X) = E_{\rho}^{*}\left(\sum_{s=1}^{S} X_{s}e_{s}\right) \le E_{\rho}^{*}(|X|) = E_{\rho}^{*}\left(\sum_{s=1}^{S} |X_{s}|e_{s}\right)$$

from monotonicity and

$$E_{\rho}^{*}(\sum_{s=1}^{S} |X_{s}|e_{s}) \le \sum_{s=1}^{S} |X_{s}|E_{\rho}^{*}(e_{s})$$

from the sub-additivity of E_{ρ}^* . But then we get

$$E^*_\rho(X) \le A \|X\|_1$$

with A is the constant defined in (2.5), hence

$$E^*_{\rho}(X) \leq E^*_{\rho}(Y) + A \|X - Y\|_1$$
$$E^*_{\rho}(Y) \leq E^*_{\rho}(X) + A \|X - Y\|_1$$

 \mathbf{SO}

(2.6)
$$|E_{\rho}^{*}(X) - E_{\rho}^{*}(Y)| \le A ||X - Y||_{1}$$

for any $X, Y \in \mathbb{R}^S$ therefore E_{ρ}^* is Lipschitz. Now put -X instead of X and -Y instead of Y in the relation (2.6) and by (2.1) the conclusion holds.

As a consequence we get the following corollary.

Corollary 2.2. The acceptance set of any coherent risk measure $\rho : \mathbb{R}^S \to \mathbb{R}$ is closed.

Proof. From (2.6) we see that the acceptance set is closed as the inverse map of a closed set of the real numbers through the continuous function ρ .

The closedness of the acceptance set of any coherent risk measure in a Euclidean space of risks is directly related to the fact that the space is finite-dimensional, as it is indicated in the proof of Proposition 2.1.

2.2. The representability of coherent risk measures in Euclidean spaces. The results of Proposition 2.1 and Corollary 2.2 are mentioned in [6, p. 5, (6)] as essential properties of a coherent risk measure when $L = L^{\infty}$.

We are going to give a complete proof of the [4, Th. 4.1] on the characterization of a coherent risk measure through a set of probability measures on the (finite) state space. Actually, we shall follow the lines of the relevant proof about L^{∞} -spaces in [6, Th. 2.3]. This Theorem, which is shown for sub(super)modular functions defined on L^{∞} , enlights several things about the set of probability vectors \mathcal{P}_{ρ} , which represents every ρ in the way that [4, Th. 4.1] indicates. For this reason we suggest its proof in a detailed form.

As $\mathbb{R}^{S}_{+} \subseteq \mathcal{A}_{\rho}$, the acceptance set of a coherent risk measure is a generating wedge since

$$\mathbb{R}^S = \mathbb{R}^S_+ - \mathbb{R}^S_+ \subseteq \mathcal{A}_
ho - \mathcal{A}_
ho \subseteq \mathbb{R}^S$$
 .

Hence \mathcal{A}^0_{ρ} is a cone. We also remark that if K is a wedge of \mathbb{R}^S , then K^0 is a closed wedge. From what we have mentioned above,

(2.7)
$$\mathcal{A}^0_{\rho} \subseteq \mathbb{R}^S_+ = (\mathbb{R}^S_+)^0$$

Hence the set

(2.8)
$$B = \{ y \in \mathcal{A}_{\rho}^{0} \mid \sum_{s=1}^{S} y_{s} = 1 \} = \Delta_{S-1} \cap \mathcal{A}_{\rho}^{0}$$

where

$$\Delta_{S-1} = \{ y \in \mathbb{R}^S_+ \mid \sum_{s=1}^S y_s = 1 \}.$$

Hence B is a bounded, closed and convex set, since the simplex Δ_{S-1} is bounded, closed and convex and \mathcal{A}^0_{a} is a closed and convex subset of \mathbb{R}^S .

Proposition 2.3. If $\rho : \mathbb{R}^S \to \mathbb{R}$ is a coherent risk measure, then it is representable as follows

(2.9)
$$\rho(X) = \sup\{\pi(-X) \mid \pi \in B\}$$

for any $X \in \mathbb{R}^S$, where B is given by (2.8).

Proof. We remark that $\rho[X + \rho(X)\mathbf{1}] = 0$ for any $X \in \mathbb{R}^S$. Hence follows

$$X + \rho(X)\mathbf{1} \in \mathcal{A}_{\rho}$$
.

Therefore by (2.7) and (2.8) we see that $\pi (X + \rho(X)\mathbf{1}) \ge 0$ for any $\pi \in B$. Hence for any $X \in \mathbb{R}^S$,

$$\pi(X) + \rho(X) \ge 0$$

for any $\pi \in B$. It follows $\rho(X) \ge \pi(-X)$ for any $\pi \in B$ which implies

(2.10)
$$\rho(X) \ge \sup\{\pi(-X) \mid \pi \in B\}$$

We have to show that the inverse inequality is also true. Let us consider some $\varepsilon > 0$. Then we obtain

$$\rho[X + (\rho(X) - \varepsilon)\mathbf{1}] = \varepsilon > 0$$

by the translation invariance property of the coherent risk measures. Hence $X + (\rho(X) - \varepsilon)\mathbf{1}$ does not belong to the acceptance set \mathcal{A}_{ρ} for any X. Now we apply the Finite Dimensional Separation Theorem on the disjoint convex sets $\{X + (\rho(X) - \varepsilon)\mathbf{1}\}\$ and \mathcal{A}_{ρ} . So from the fact that $0 \in \mathcal{A}_{\rho}$, for any X there exists some $\pi_0 \in B$ (which depends on X and $\varepsilon > 0$) such that

$$\pi_0 \left(X + (\rho(X) - \varepsilon) \mathbf{1} \right) = \pi_0(X) + \rho(X) - \varepsilon < 0.$$

The sets separated are the following: the first one is the singleton $\{X + (\rho(X) - \varepsilon)\mathbf{1}\}$ being a compact set and the second one is acceptance set \mathcal{A}_{ρ} which is closed in \mathbb{R}^{S} from the continuity of ρ (Corollary 2.2). Hence, there is some $\delta > 0$ and some $\alpha \in \mathbb{R}$ such that for this $\pi_{0} \neq 0$ we obtain

$$\pi_0(X + (\rho(X) - \varepsilon)\mathbf{1}) \le \alpha < \alpha + \delta \le \pi_0(Y),$$

for any $Y \in \mathcal{A}_{\rho}$. Then π_0 takes positive values on \mathcal{A}_{ρ} . This holds because if we suppose that there is some $Y \in \mathcal{A}_{\rho}$ such that $\pi_0(Y) < 0$ then we come to a contradiction. Indeed, since $\lambda Y \in \mathcal{A}_{\rho}$, then for $\lambda \to +\infty$,

$$\pi_0(\lambda Y) \to -\infty$$

which contradicts the above separation. Since $\pi_0 \in \mathcal{A}^0_{\rho} \subseteq \mathbb{R}^S_+$ and $\pi_0 \neq 0$,

$$\frac{1}{\sum_{s=1}^{S} \pi_0(s)} \pi_0 \in B \,,$$

and we denote the last vector also by π_0 . We remark that the supremum in (2.10) is finite for any X since B is a compact set and -X may be viewed as a continuous linear functional of \mathbb{R}^S which actually takes a maximum value on the compact set B.

Hence for this X and this $\varepsilon > 0$, we obtain

(2.11)
$$\rho(X) - \varepsilon < \pi_0(-X) \le \sup\{\pi(-X) \mid \pi \in B\}.$$

From the inequality (2.11) and for this X if we put $\varepsilon_n = 1/n$ for any $n \in \mathbb{N}$, we get

$$\rho(X) - \frac{1}{n} \le \sup\{\pi(-X) \mid \pi \in B\}$$

and by taking the limit of the sequence $\rho(X) - 1/n$, $n \in \mathbb{N}$ we get

$$\rho(X) \le \sup\{\pi(-X) \mid \pi \in B\}$$

as desired.

The set B is actually the desired set of probabilities indicated in [4, Th. 4.1]. The representability of a coherent risk measure ρ when the set of states is the finite set $\{1, 2, \ldots, S\}$, indicates that a risk measure is coherent if and only if there is a set of probability vectors \mathcal{P} for the set of states $\{1, 2, \ldots, S\}$ such that

$$\rho(X) = \sup_{P \in \mathcal{P}} E_P(-X) \,,$$

where $E_P(-X)$ denotes the expectation of -X under the probability vector P. The one direction of representability which is not so obvious is indicated by the Proposition 2.3. The other, much easier, is presented for completeness in the following.

Proposition 2.4. The function $\rho_{\mathcal{P}} : \mathbb{R}^S \to \mathbb{R}$, where

(2.12)
$$\rho_{\mathcal{P}}(X) = \sup_{P \in \mathcal{P}} E_P(-X)$$

and \mathcal{P} is a set of probability vectors for the set of states, is a coherent risk measure.

Proof. Let us check the four properties of the coherent measures.

(*i*) (Translation Invariance):

$$\rho_{\mathcal{P}}(X + a\mathbf{1}) = \sup\{E_P(-X - a\mathbf{1}) \mid P \in \mathcal{P}\} = \sup\{E_P(-X) - aE_P(\mathbf{1}) \mid P \in \mathcal{P}\}\$$

= $\sup\{E_P(-X) - a \mid P \in \mathcal{P}\} = \sup\{E_P(-X) \mid P \in \mathcal{P}\} - a = \rho_{\mathcal{P}}(X) - a,$

for any $X \in \mathbb{R}^S$ and any $a \in \mathbb{R}$.

(*ii*) (Sub-additivity):

$$\rho_{\mathcal{P}}(X+Y) = \sup\{E_P(-X-Y) \mid P \in \mathcal{P}\} = \sup\{E_P(-X) + E_P(-Y) \mid P \in \mathcal{P}\}$$

$$\leq \sup\{E_P(-X) \mid P \in \mathcal{P}\} + \sup\{E_P(-Y) \mid P \in \mathcal{P}\} = \rho_{\mathcal{P}}(X) + \rho_{\mathcal{P}}(Y),$$

for any $X, Y \in \mathbb{R}^S$.

(*iii*) (Positive Homogeneity):

$$\rho_{\mathcal{P}}(\lambda X) = \sup\{E_P(-\lambda X) \mid P \in \mathcal{P}\} = \sup\{\lambda E_P(-X) \mid P \in \mathcal{P}\}\$$
$$= \lambda \sup\{E_P(-X) \mid P \in \mathcal{P}\} = \lambda \rho_{\mathcal{P}}(X)$$

for any $X \in \mathbb{R}^S$ and any $\lambda \in \mathbb{R}_+$.

(iv) (Monotonicity): If $Y \ge X$ in the usual partial ordering of \mathbb{R}^S , then $-X \ge -Y$, hence

$$E_P(-X) \ge E_P(-Y)$$

for any $P \in \mathcal{P}$. Taking suprema over \mathcal{P} we get that

$$\rho_{\mathcal{P}}(X) = \sup_{P \in \mathcal{P}} E_P(-X) \ge \sup_{P \in \mathcal{P}} E_P(-Y) = \rho_{\mathcal{P}}(Y).$$

2.3. The Relevance property. Finally, another question about coherent risk measures when the set of states of the world is finite is the so-called Relevance property, mentioned in [4], p. 210. The Relevance property for a risk measure $\rho : \mathbb{R}^S \to \mathbb{R}$ says that if $X \in -\mathbb{R}^S_+$ and $X \neq 0$, then $\rho(X) > 0$. If the risk measure is coherent, then a weaker property can be proved due to the properties of it. The fact that the set of states of the world is finite plays an important role in the deduction of this property. The property and its proof are given in the following proposition

Proposition 2.5. If $\rho : \mathbb{R}^S \to \mathbb{R}$ is a coherent risk measure, then for any $X \in -\mathbb{R}^S_{++}$, $\rho(X) > 0$ holds.

Proof. By subadditivity of ρ we take $\rho(0) = 0 \leq \rho(X) + \rho(-X)$. This implies $-\rho(-X) \leq \rho(X)$ and since $-X \in \mathbb{R}^{S}_{++} \subseteq \mathcal{A}_{\rho}$, we take $\rho(-X) \leq 0$. Hence $\rho(X) \geq 0$. But since $X \in -\mathbb{R}^{S}_{++}$, we pose $2k = \max\{X_{s}|s = 1, 2, ..., S\} < 0$ and then $\rho(X - k\mathbf{1}) = \rho(X) + k$ by the Translation Invariance property. But we notice that $X + k\mathbf{1} \in -\mathbb{R}^{S}_{++}$ since for any state s we have $2X_{s} < X_{s} \leq \max\{X_{s}|s = 1, 2, ..., S\}$. By the first remark we made, we take $\rho(X - k\mathbf{1}) = \rho(X) + k \geq 0$. Hence $\rho(X) \geq -k > 0$ and the conclusion is ready.

Of course, the above version of the Relevance property can be deduced by the representation of a coherent risk measure. If $X \in -\mathbb{R}^{S}_{++}$, then $-X \in \mathbb{R}^{S}_{++}$ which means that there is some $\delta > 0$ such that $X_s \ge \delta > 0$ for any s = 1, 2, ..., S. From the representation theorem 2.3, we get that for any $\pi \in \mathcal{A}^0_{\rho} \cap \Delta_{S-1} \pi(-X) = \pi \cdot (-X) \ge \delta > 0$. Hence $\rho(X) = \sup\{\pi(-X) | \pi \in \mathcal{A}^0_{\rho} \cap \Delta_{S-1}\} \ge \delta > 0$.

3. Portfolio theory and coherent risk measures-Markowitz type problems

We name 'Markowitz type problems' those portfolio selection problems in which the coherent risk measures play a role equivalent to the one of standard deviation in Markowitz model. Under the Markowitz framework, the portfolio selection is generally determined by the optimization principle 'maximize the expected return, while you should minimize the risk'. If the measurement of risk is determined by some coherent risk measure ρ , then the 'expected return, risk pair' for any financial position $X \in \mathbb{R}^S$ is the pair

$$(\mathbb{E}(X), \rho(X))$$

of real numbers, where $\mathbb{E}(X)$ denotes the mean value of X under the statistical measure of the market μ and $\rho(X)$ is the risk of X with respect to ρ , or else the amount of money needed so that X is acceptable under ρ . If we consider a set of positions \mathcal{X} among which an investor chooses her portfolio, then the (μ, ρ) -primarily desirable set of positions is

(3.13)
$$K_1(\mathcal{X}) = \{ X \in \mathcal{X} | \mathbb{E}(X) \ge 0, \rho(X) \le 0 \}$$

and the (μ, ρ) - desirable set of positions at the risk level $c \in \mathbb{R}$ is

(3.14)
$$K_2(\mathcal{X}) = \{ X \in \mathcal{X} | \mathbb{E}(X) \ge 0, \rho(X) \le c \}.$$

The expected return-risk pairs of $K_i(\mathcal{X})$, i = 1, 2 with respect to ρ is the following set of \mathbb{R}^2 :

(3.15)
$$K_{(\mathbb{E},\rho),i}(\mathcal{X}) = \{ (\mathbb{E}(X), \rho(X)) | X \in K_i(\mathcal{X}) \}, i = 1, 2$$

The efficiency frontier of $K_i(\mathcal{X})$, i = 1, 2 is the set of Pareto efficient points $E(K_{(\mathbb{E},\rho),i}(\mathcal{X}), D)$ of $K_i(\mathcal{X})$ with respect to the cone $D = \{x = (x_1, x_2) \in \mathbb{R}^2 | x_1 \ge 0, x_2 \le 0\}$ of \mathbb{R}^2 . This set is consisted by the pairs $(\mathbb{E}(X), \rho(X)), X \in K_i(\mathcal{X}), i = 1, 2$, such that there is not any position X_0 in $K_i(\mathcal{X})$ such that either $\mathbb{E}(X_0) > \mathbb{E}(X)$, while $\rho(X_0) \le \rho(X)$, or $\mathbb{E}(X_0) \ge \mathbb{E}(X)$, while $\rho(X_0) < \rho(X)$. The solutions to the maximization problem

(3.16)
$$Maximize \mathbb{E}(X) - \lambda \rho(X) \text{ subject to } X \in K_i(\mathcal{X}), i = 1, 2,$$

are also elements of the efficiency frontier if $\lambda \in \mathbb{R}_+$, $\lambda \neq 0$, because the functional $(1, -\lambda)$ is a strictly positive functional of D and the set of *positive proper efficient points* is a subset of the set of Pareto efficient points. The determination either of the solution set of the vector optimization problems 3.13 or 3.14 (which are portfolio selection problems anyway), gives rise to the solution of the scalar optimization problem 3.16. For the solution set $S_{\lambda}(K_{(\mathbb{E},\rho),i}(\mathcal{X}))$ of 3.16

$$S_{\lambda}(K_{(\mathbb{E},\rho),i}(\mathcal{X})) \subseteq PosE(K_{(\mathbb{E},\rho),i}(\mathcal{X}), D) \subseteq E(K_{(\mathbb{E},\rho),i}(\mathcal{X}), D)), \ \lambda > 0, i = 1, 2.$$

The existence of Pareto efficient points is assured mainly by the theorem of J. Borwein, proved in [5] and is also stated in the book [8]. We may remark that due to the continuity of the maps $\mathbb{E}(.), \rho(.)$ on \mathbb{R}^S , the properties of the boundedness and the closedness of \mathcal{X} are

transferred into the set $K_{(\mathcal{E},\rho),i}(\mathcal{X})$ which is examined for the existence of Pareto efficient points or positive proper efficient points. We may see that the following proposition is true:

Proposition 3.1. The functional $\mathcal{T} = (\mathbb{E}(.), \rho(.)) : \mathbb{R}^S \to \mathbb{R}^2$ is continuous. Hence if \mathcal{X} is closed, then $\mathcal{T}(\mathcal{X})$ is closed and if \mathcal{X} is bounded, then $\mathcal{T}(\mathcal{X})$ is bounded.

Proof. Suppose that \mathbb{R}^S is endowed with the $\|.\|_1$ -norm.

$$\mathbb{E}(X) = \sum_{i=1}^{S} \mu_s X_s \le \max\{\mu_s | s = 1, 2..., S\} \|X\|_1,$$
$$\rho(X) \le A \|X\|_1,$$

imply continuity of \mathcal{T} . The second inequality is proved in 2.1.

For the (μ, ρ) -optimization, see in [10]. For the notions concerning vector optimization, see in [8].

4. Portfolio theory and coherent risk measures-Utility type problems

We name 'utility type problems' those portfolio selection problems in which the coherent risk measures play a role equivalent to the one of a utility function in classical microeconomic theory. Hence a common class of portfolio selection problems is the *risk minimization problems*. The general form of these problems is the following:

$$(4.17) Minimize \ \rho(X) \ subject \ to \ X \in \mathcal{X},$$

where ρ is a coherent risk measure and $\mathcal{X} \subseteq \mathbb{R}^S$ is a non-empty set of financial positions. The problem 4.17 corresponds to the determination of the set of financial positions which minimize the risk with respect to ρ among the positions in \mathcal{X} . Among the conditions of normality for the constrained optimization problem 4.17, the more important are *convexity*, *closedness* and *boundedness* of \mathcal{X} . Various combinations of these properties are related to the existence and the uniqueness of solution to 4.17, combinations which are related to the form of the set \mathcal{X} of constraints. For the determination of the solution to these problems standard optimization techniques are used, like the Kuhn-Tucker one. For the utility based problems of portfolio selection, see [11].

Let us remind some essential propositions on existence and uniqueness.

Proposition 4.1. 4.17 has a solution if \mathcal{X} is closed and bounded.

Proof. ρ as a coherent risk measure is continuous on \mathbb{R}^S . \mathcal{X} is compact, hence by the Weierstrass theorem the conclusion is ready.

Proposition 4.2. If 4.17 has a solution and \mathcal{X} is convex, then the solution set is an extreme set of it.

Proof. The solution set is the following: $M = \{X \in C | \rho(X) = \sup\{\rho(Y) | Y \in C\}$. Suppose that M is not an extreme set. Then, there are some $y_0, z_0 \in M$ and some $a_0 \in (0, 1)$ such that $a_0y_0 + (1 - a_0)z_0 \in M$, while $y_0, z_0 \notin M$. Since ρ is a convex function, $\rho(a_0y_0 + (1 - a_0)z_0) \leq a_0\rho(y_0) + (1 - a_0)\rho(z_0)$. But since $z_0, y_0 \notin M$, $\rho(a_0y_0 + (1 - a_0)z_0) > \rho(z_0) > (1 - a_0)\rho(z_0)$, $\rho(a_0y_0 + (1 - a_0)\rho(z_0) > \rho(y_0) > a_0\rho(y_0)$ which implies $\rho(a_0y_0 + (1 - a_0)z_0) > a_0\rho(y_0) + (1 - a_0)\rho(z_0)$, a contradiction.

Proposition 4.3. If \mathcal{X} is convex, closed and bounded, then 4.17 has a solution which is an extreme point of \mathcal{X} .

Proof. ρ as a coherent risk measure is continuous on \mathbb{R}^S . \mathcal{X} is compact and oonvex. The set $M = \{X \in C | \rho(X) = \sup\{\rho(Y) | Y \in C\}$ is an extreme subset of C and by previous proposition is non-empty. By Zorn's Lemma, there is an extreme point of C in M (see also Lemma 5.114 in [1])

5. Appendix: notions from the theory of partially ordered linear spaces

In this paragraph, we give some essential notions and results from the theory of partially ordered linear spaces which are used in this paper. Let L be a (normed) linear space. A set $C \subseteq L$ satisfying $C + C \subseteq C$ and $\lambda C \subseteq C$ for any $\lambda \in \mathbb{R}_+$ is called *wedge*. A wedge for which $C \cap (-C) = \{0\}$ is called *cone*. A pair (E, \geq) where E is a linear space and \geq is a binary relation on E satisfying the following properties:

- (i) $x \ge x$ for any $x \in L$ (reflexive)
- (ii) If $x \ge y$ and $y \ge z$ then $x \ge z$, where $x, y, z \in E$ (transitive)
- (*iii*) If $x \ge y$ then $\lambda x \ge \lambda y$ for any $\lambda \in \mathbb{R}_+$ and $x + z \ge y + z$ for any $z \in L$, where $x, y \in L$ (compatible with the linear structure of L),

is called *partially ordered linear space*. The binary relation \geq in this case is a *partial ordering* on E. The set $P = \{x \in E | x \geq 0\}$ is called *(positive) wedge* of the partial ordering \geq of E. Given a wedge C in E, the binary relation \geq_C defined as follows:

$$x \ge_C y \iff x - y \in C_1$$

is a partial ordering on L, called *partial ordering induced by* C on L. If the partial ordering \geq of the space E is *antisymmetric*, namely if $x \geq y$ and $y \geq x$ implies x = y, where $x, y \in E$, then C is a cone.

Then (L, \geq) is called a *partially ordered linear space*.

A non-empty subset K of a vector space L is called *wedge* if it satisfies

(1) $K + K \subseteq K$

(2) $\lambda K \subseteq K$ for any real number $\lambda \ge 0$.

A non-empty subset C of X is called *cone* if it is a wedge which satisfies

(5.1)
$$C \cap (-C) = \{0\}.$$

Any cone C in a vector space L implies a partial ordering relation \geq_C on it defined as follows:

(5.2)
$$x \ge_C y \Leftrightarrow x - y \in C.$$

When $x \ge_C y$ and $x - y \ne 0$ then we write x > y. When we write $y \le x$ with respect to the same partial ordering relation implied by C on L, we mean that $x \ge y$. In this case the partially ordered linear space (L, \ge_C) may be denoted by (L, C). On the other hand, if (L, \ge) is a partially ordered linear space, then the set

$$P = \{x \in L \mid x \ge 0\}$$

is a cone and $\geq \geq_P$ coincide.

A linear functional f of a vector space L is called *positive functional* of the partially ordered linear space (L, K) (or a *positive functional of* K) if

$$f(x) \ge 0, \ \forall x \in K,$$

and strictly positive functional of the ordered linear space (L, K) (or a strictly positive functional of K) if it is positive and

$$f(x) > 0, \ \forall x \in K \setminus (K \cap (-K))$$

if K is a wedge, while

$$f(x) > 0, \ \forall x \in K \setminus \{0\}$$

if K is a cone. If L is a normed linear space and C is a cone, a linear functional of L is uniformly monotonic if $f(x) \ge a ||x||$ for any $x \in C \setminus \{0\}$ for some $a \in \mathbb{R}_+ \setminus \{0\}$.

In this article, since the spaces we use are also normed linear spaces, when we refer to positive or strictly positive functionals we mean continuous linear functionals (elements of the norm dual space L^*).

If K is a wedge of the normed linear space L, the dual wedge of K, denoted by K^0 , represents the following subset of L^* :

$$K^{0} = \{ f \in L^{*} \mid f(x) \ge 0, \ \forall x \in K \}.$$

If K is a wedge with $K \subseteq C$ then $C^0 \subseteq K^0$. In the rest of this article we will denote by L^0_+ the dual wedge of L_+ .

If (L, C) is a partially ordered linear space and C is a cone, then a *base* of C is any convex subset B of C such that for any $x \in C \setminus \{0\}$ there exists a unique $\lambda_x \in \mathbb{R}_+ \setminus \{0\}$ such that $\lambda_x x \in B$. If f is a strictly positive functional of L_+ , the set

(5.3)
$$B_f = \{x \in C \mid f(x) = 1\},\$$

is the base of C defined by f. The base B_f is bounded if and only if f is uniformly monotonic. If B is a bounded base of C such that $0 \notin \overline{B}$ then C is called *well-based*. If C is well-based, then a bounded base of C defined by a $g \in L^*$ exists.

Let us denote by [x, y] the order interval of L defined by x, y, i.e.

$$[x,y] = (x+K) \cap (y-K).$$

An element $e \in L$ is called *order-unit* of (L, K) if

$$L = \bigcup_{n=1}^{\infty} [-ne, ne].$$

If L is also a normed linear space, then according to [9, Pr. 3.1.3], e is an interior point of K in terms of the norm topology if and only if [-e, e] is a neighborhood of zero. Hence an interior point of K is an order-unit of (L, K).

(L, K) is a vector lattice if for any $x, y \in L$, the supremum and the infimum of $\{x, y\}$ with respect to the partial ordering defined by K exist in L. In this case $\sup\{x, y\}$ and $\inf\{x, y\}$ are denoted by $x \lor y, x \land y$ respectively. If so,

$$|x| = \sup\{x, -x\}$$

is the *absolute value* of x and if L is also a normed space such that

$$|| |x| || = ||x||$$

for any $x \in L$, then (L, K) is called *normed lattice*.

A wedge K of L is called *generating* if the subspace K - K it generates in L is equal to L itself. If K is a generating wedge in L, then K^0 is a cone of L^* .

Let us note that the usual partial ordering relation on \mathbb{R}^S is defined as follows: $x \ge y$ if and only if $x_s \ge y_s$ for any $s = 1, 2, \ldots, S$, where $x, y \in \mathbb{R}^S$. The positive cone of this ordering is denoted by \mathbb{R}^{S}_{+} . Also, the usual partial ordering of an $L^{p}(\Omega, \mathcal{F}, \mu)$ space, where $(\Omega, \mathcal{F}, \mu)$ is a probability space is the following: $X \geq Y$ if and only if the set

 $\{\omega \in \Omega : X(\omega) > Y(\omega)\}$

is a set of probability 1.

We remind the following essential result about wedges in Euclidean spaces: Consider some wedge K of the space \mathbb{R}^S . Then $K^{00} = (K^0)^0 = \overline{K}$. Throughout the article we suppose that the cone L_+ of L is $\sigma(L, L^*)$ -closed and we need the following result.

Proposition 5.1. L^0_+ is a $\sigma(L^*, L)$ - closed subset of L^* .

Proof. Consider a net $(p_{\lambda})_{\lambda \in \Lambda} \subseteq L^0_+$ such that

$$p_{\lambda} \stackrel{\sigma(L^*,L)}{\to} p$$
,

. Then $p_{\lambda}(X) \geq 0$ for any $X \in L_+$. From the weak-star convergence of $(p_{\lambda})_{\lambda \in \Lambda}$ we get $p_{\lambda}(Y) \to p(Y)$ for any $Y \in L$, hence the same holds for any $Y \in L_+$. Hence for any $Y \in L_+$, p(Y) is the limit of a convergent net consisted by positive real numbers. Finally, we get that $p(Y) \ge 0$ for any $Y \in L_+$ which implies $p \in L^0_+$.

Proposition 5.2. If the cone L_+ of L is $\sigma(L, L^*)$ -closed and L is reflexive, then

(5.4)
$$(L^0_+)^0 := L^{00}_+ = L_+$$

Proof. It suffices to show that $L_+ \subseteq L^{00}_+$ and $L^{00}_+ \subseteq L_+$. Let $X \in L_+$. Then $X \in L^{00}_+$ since $L^{00}_+ = \{Y \in L^{**} \mid Y(\pi) \ge 0, \text{ for any } \pi \in L^0_+\}$. Since L is reflexive, $L^{00}_{+} = \{Y \in L | \hat{Y}(\pi) \geq 0, \text{ for any } \pi \in L^{0}_{+}\}$. As far as $X \in L_{+}$, then $\hat{X}(\pi) = \pi(X) \ge 0$ for any $\pi \in L^0_+$, and the inclusion $L_+ \subseteq L^{00}_+$ is deduced.

For the converse inclusion let us suppose that there were some $Y_0 \in L^{00}_+$ for which $Y_0 \notin L_+$. Since L_+ is a weakly closed and convex set, while the singleton $\{Y_0\}$ is a weakly compact set, which is also convex. Then, from the Separation Theorem for disjoint convex sets in locally convex spaces (see for example [2, Th. 5.58]), there is some $\pi_0 \in L^*, \pi \neq 0$ which strongly separates them. In other words, there is some $\alpha \in \mathbb{R}$ and some $\delta > 0$ such that

(5.5)
$$\pi_0(Y_0) \le \alpha < \alpha + \delta \le \pi_0(Y)$$

for any $Y \in L_+$. Since L_+ is a wedge, π_0 takes positive values on the elements of it, since if we suppose that there is some $Y_1 \in L_+$ such that $\pi_0(Y_1) < 0$, then if $\lambda \to +\infty$, $\lambda Y_1 \in L_+$ and

$$\pi_0(\lambda Y_1) = \lambda \pi_0(Y_1) \to -\infty \,,$$

a contradiction from the separation argument. Hence, π_0 takes positive values on L_+ , thus $\pi_0 \in L^0_+$. For Y = 0 we obtain from (5.5), $\pi_0(Y_0) < 0$, while we supposed that $Y_0 \in L^{00}_+$, which implies $\hat{Y}_0(\pi_0) = \pi_0(Y_0) \ge 0$. This is a contradiction deduced from the assumption that such a Y_0 exists. Namely, the inverse inclusion $L^{00}_+ \subseteq L$ is also true.

Lemma 5.3. If C is a closed wedge of some normed linear space L then the condition $C^0 = \{0\}$ is equivalent to C = L.

Proof. If C = L then if $y_0 \in C^0$ $y_0(x) \ge 0$ for any $x \in L$, which implies $y_0(-x) = -y_0(x) \ge 0$. Then for any $x \in L$, we get $y_0(x) = 0$ and by the properties of $\langle L, L^* \rangle$ as a dual pair (see for example Definition 5.79 in [1]) we get $y_0 = 0$. On the other hand, if C is such that $C^0 = \{0\}$,

then if we suppose that there is some $x_0 \in L \setminus C$, then by applying the Strong Separation Theorem for disjoint convex sets in locally convex spaces, we have that $\{x_0\}$ is a compact convex set and C is a closed convex set in L which are disjoint. This implies the existence of some $f \in L^*, f \neq 0$ and of some $a \in \mathbb{R}, \delta > 0$ such that

$$f(x_0) \le a < a + \delta \le f(c),$$

for any $c \in C$. But f takes positive values on C since if there is some c_0 with $f(c_0) < 0$ then for $\lambda \to \infty$ we would take that $\lim_{\lambda\to\infty} f(\lambda c_0) = -\infty$, while $\lambda c_0 \in C$ since C is a wedge. But in this case the separation condition would be violated and this is a contradiction. Hence $f \in C^0 = \{0\}$, a contradiction since $f \neq 0$ by the separation argument. We were led to a contradiction by supposing that a $x_0 \in L \setminus C$ exists. Hence C = L and the conclusion is ready. \Box

6. Appendix: Vector Optimization, Convexity

Let L be a normed linear space partially ordered by the cone P and let C be a non-empty set of L. In an equivalent way, the set of maximal points of C with respect to P is the set of $y \in C$ such that $C \cap (y + P) = \{y\}$. The set of the maximal points of C with respect to P is denoted by $E_M(C, P)$ or E(C, P), called set of Pareto efficient points of C (with respect to P). The set which consists of the solution sets of any maximization problem of the form

(6.6)
$$Maximize \ f(x) \ subject \ to \ x \in C$$
,

where f is a strictly positive functional of P is denoted by PosE(C, P) and it is a subset of E(C, P) (see [8]) called set of positive proper Pareto efficient points of C (with respect to P).

Theorem 6.1. (Essential theorem about existence of efficient points- [5]) Let C be a nonempty subset of a partially ordered topological linear space L partially ordered by a closed cone P. Then :

- (i) If the set C has a closed section which has an upper bound and the ordering cone P is Daniell, then there is at least one maximal element of C.
- (ii) If the set C has a closed and bounded section, the ordering cone P is Daniell and X is boundedly order complete, then there is at least one maximal element of C.
- (iii) If the set C has a compact section, then there is at least one maximal element of the set C.

The subset $C \cap (y + P) = C_y$ of C is called *y*-section of C or else section of C defined by y.

A topological linear space L is L is *boundedly order complete* if for every bounded increasing net in the space X, the supremum of the elements of it exists. A cone P of a linear topological space L is called *Daniell cone* if every increasing net of L which is upper bounded converges to its supremum.

Note that every closed cone in a Euclidean space is Daniell and every Euclidean space partially ordered by a closed cone is boundedly order complete (nets in these case are replaced by sequences).

A subset F of a convex set C in L is called *extreme set* or else *face* of C, if whenever $x = az + (1 - a)y \in F$, where 0 < a < 1 and $y, z \in C$ implies $y, z \in F$. If F is a singleton, F is called *extreme point* of C.

References

- [1] ALIPRANTIS, C.D., BURKINSHAW, O. (1998) Principles of Real Analysis (fifth edition), Academic Press
- [2] ALIPRANTIS, C.D., BORDER, K.C. (1999) Infinite Dimensional Analysis, A Hitchhiker's Guide (second edition), Springer
- [3] ALIPRANTIS, C.D., BURKINSHAW, O. (1985) Positive Operators, Academic Press: San Diego, New York
- [4] ARTZNER, P., DELBAEN, F., EBER, J.M., HEATH, D. (1999) Coherent measures of risk, Mathematical Finance 9, 203-228
- [5] BORWEIN, J.M. (1983) On the existence of Pareto efficient points, Mathematics of Operations Research 8, 64-73
- [6] DELBAEN, F. (2002) Coherent risk measures on general probability spaces. In Advances in finance and stochastics: essays in honour of Dieter Sondermann, Springer-Verlag: Berlin, New York, 1-38
- [7] HUBER, P. (1981) Robust Statistics, Wiley: New York
- [8] JAHN, J. (2004) Vector Optimization, Springer
- [9] JAMESON, G. (1970) Ordered Linear Spaces, Lecture Notes in Mathematics 141, Springer-Verlag
- [10] JASCHKE, S., KÜCHLER, U. (2001) Coherent risk measures and good-deal bounds, Finance and Stochastics 5, 181-200
- [11] ROCKAFELLAR, T.R., URYASEV, S., ZABARANKIN, M. (2003) Deviation measures in risk analysis and optimization, Research Report 2002-7, Risk Management and Financial Engineering Lab, Departmet of Industrial and Systems Engeineering, University of Florida

Note: Great part of the first two paragraphs of this text arised during writing a research paper jointly with Prof. D.G. Konstantinides.